

Reconstructing and Rendering Shiny Surface with Hybrid Neural Fields

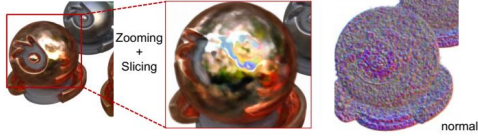
Ruofan Liang

Department of Computer Science, University of Toronto

Motivation

Problem: Reconstructing high-quality shiny 3D objects is still a problem for NeRF. Surface quality and *rendering* quality cannot be obtained at the same time (i.e., *appearance & geometry ambiguity* [5]).

- Some work achieves higher rendering quality but has erroneous surface.
- Some work achieves smooth surface reconstruction but lacks object details.



Existing work that tackle this problem:

Ref-NeRF [1], VolSDF [2], NeuS [3], ...

These methods rely on **fully implicit MLP** and take **very long time to train** (days of).

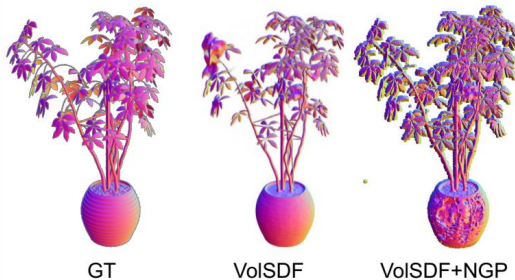
However, simply replacing pure MLP model with **hybrid model** (e.g., Instant-NGP [4]) for speedup will deteriorate the surface quality a lot because of discrete neural feature in hybrid model. Hence,

- Extra constraints need to be considered.

Goal: We want to achieve better *rendering* and *surface* reconstruction results for shiny objects, with much *faster speed* by using hybrid NeRF models.

Observations

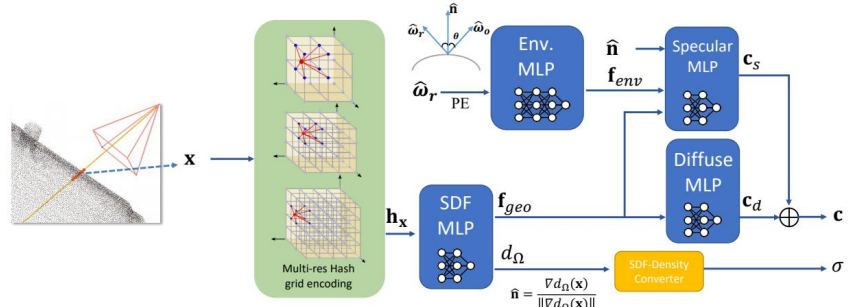
What if we simply replace the fully implicit MLP with Instant-NGP and keep the rest parts unchanged (including Eikonal regularization)?



References

- [1] Verbin, Dor, et al. "Ref-nerf: Structured view-dependent appearance for neural radiance fields." CVPR, 2022.
- [2] Yariv, Lior, et al. "Volume rendering of neural implicit surfaces." NeurIPS, 2021.
- [3] Wang, Peng, et al. "Neus: Learning neural implicit surfaces by volume rendering for multi-view reconstruction." NeurIPS, 2021.
- [4] Müller, Thomas, et al. "Instant neural graphics primitives with a multiresolution hash encoding." SIGGRAPH, 2022
- [5] Zhang, Kai, et al. "Nerf++: Analyzing and improving neural radiance fields." preprint arXiv:2010.07492 (2020).

Overview



- Instant-NGP like hybrid model with SDF-based volume density (e.g., VolSDF).
- Decomposing color with diffuse and specular color with two shallow MLP branches.
- Using a relatively large env. MLP with reflected direction as the only input to implicitly learn global illumination from environment.

SDF Constraints

Additional constraints for hybrid NeRF models:

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- SDF continuity regularization

$$\mathcal{L}_d = \sum \|\Delta d_\Omega(\mathbf{x}_t) - (\hat{\mathbf{n}} \cdot \hat{\mathbf{v}}) \delta_t\|^2$$

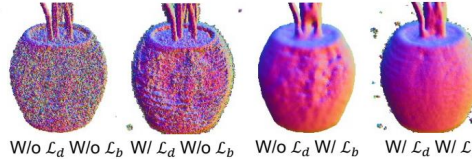
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- Back face suppression

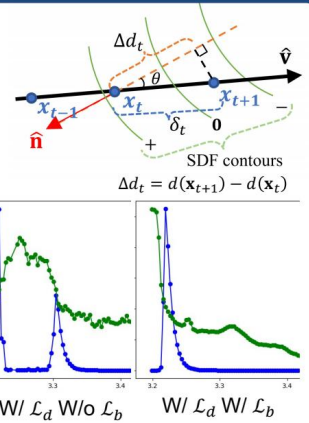
$$\mathcal{L}_b = \sum \max(\Delta d_t, 0) \frac{w_i \Delta d_t}{\delta_t^2 + \Delta d_t^2}$$

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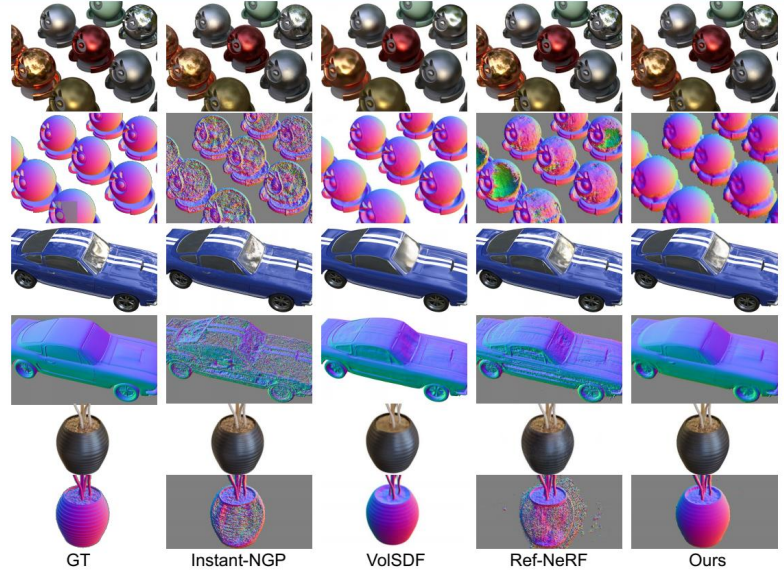
- No Eikonal loss used.



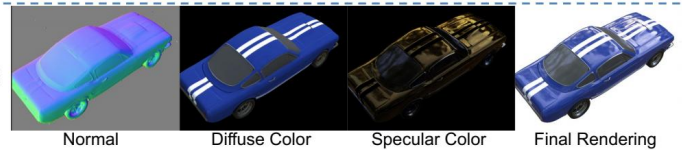
* Evaluated only after ~100 epoch, no env MLP is used.



Experimental Results



Our Decomposition:



	PSNR↑			SSIM↑			LPIPS↓			MAE↓		
	ficus	materials	car	ficus	materials	car	ficus	materials	car	ficus	materials	car
iNGP	31.68	28.07	26.14	0.988	0.962	0.939	0.015	0.034	0.061	61.35	70.81	73.25
VolSDF	24.26	28.56	27.02	0.957	0.966	0.951	0.059	0.041	0.055	46.58	32.49	46.92
RefNeRF	<u>29.88</u>	33.06	30.01	<u>0.982</u>	0.987	<u>0.967</u>	0.021	0.013	0.026	68.00	42.48	57.19
Ours	29.23	29.44	29.50	0.982	0.971	0.969	0.020	0.026	0.036	41.46	21.09	50.64
RefNeRF*	33.91	35.41	30.82	0.983	0.983	0.955	0.019	0.022	0.041	41.05	9.53	14.93

RefNeRF* are the report scores in the original paper.